EXAMPLE 1 If
$$D = \begin{bmatrix} 5 & 0 \\ 0 & 3 \end{bmatrix}$$
, then $D^2 = \begin{bmatrix} 5 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 5 & 0 \\ 0 & 3 \end{bmatrix} = \begin{bmatrix} 5^2 & 0 \\ 0 & 3^2 \end{bmatrix}$ and

$$D^3 = DD^2 = \begin{bmatrix} 5 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 5^2 & 0 \\ 0 & 3^2 \end{bmatrix} = \begin{bmatrix} 5^3 & 0 \\ 0 & 3^3 \end{bmatrix}$$

In general,

$$D^k = \begin{bmatrix} 5^k & 0 \\ 0 & 3^k \end{bmatrix} \quad \text{for } k \ge 1$$

If $A = PDP^{-1}$ for some invertible P and diagonal D, then A^k is also easy to compute, as the next example shows.

EXAMPLE 2 Let
$$A = \begin{bmatrix} 7 & 2 \\ -4 & 1 \end{bmatrix}$$
. Find a formula for A^k , given that $A = PDP^{-1}$, where
$$P = \begin{bmatrix} 1 & 1 \\ -1 & -2 \end{bmatrix} \text{ and } D = \begin{bmatrix} 5 & 0 \\ 0 & 3 \end{bmatrix}$$

THEOREM 5 The Diagonalization Theorem

An $n \times n$ matrix A is diagonalizable if and only if A has n linearly independent eigenvectors.

In fact, $A = PDP^{-1}$, with D a diagonal matrix, if and only if the columns of P are n linearly independent eigenvectors of A. In this case, the diagonal entries of D are eigenvalues of A that correspond, respectively, to the eigenvectors in P.

Diagonalizing Matrices

EXAMPLE 3 Diagonalize the following matrix, if possible.

$$A = \begin{bmatrix} 1 & 3 & 3 \\ -3 & -5 & -3 \\ 3 & 3 & 1 \end{bmatrix}$$

That is, find an invertible matrix P and a diagonal matrix D such that $A = PDP^{-1}$.

EXAMPLE 4 Diagonalize the following matrix, if possible.

$$A = \begin{bmatrix} 2 & 4 & 3 \\ -4 & -6 & -3 \\ 3 & 3 & 1 \end{bmatrix}$$

THEOREM 6 An $n \times n$ matrix with n distinct eigenvalues is diagonalizable.

EXAMPLE 5 Determine if the following matrix is diagonalizable.

$$A = \begin{bmatrix} 5 & -8 & 1 \\ 0 & 0 & 7 \\ 0 & 0 & -2 \end{bmatrix}$$

THEOREM 7 Let A be an $n \times n$ matrix whose distinct eigenvalues are $\lambda_1, \ldots, \lambda_p$.

- a. For $1 \le k \le p$, the dimension of the eigenspace for λ_k is less than or equal to the multiplicity of the eigenvalue λ_k .
- b. The matrix A is diagonalizable if and only if the sum of the dimensions of the eigenspaces equals n, and this happens if and only if (i) the characteristic polynomial factors completely into linear factors and (ii) the dimension of the eigenspace for each λ_k equals the multiplicity of λ_k .
- c. If A is diagonalizable and \mathcal{B}_k is a basis for the eigenspace corresponding to λ_k for each k, then the total collection of vectors in the sets $\mathcal{B}_1, \ldots, \mathcal{B}_p$ forms an eigenvector basis for \mathbb{R}^n .

EXAMPLE 6 Diagonalize the following matrix, if possible.

$$A = \begin{bmatrix} 5 & 0 & 0 & 0 \\ 0 & 5 & 0 & 0 \\ 1 & 4 & -3 & 0 \\ -1 & -2 & 0 & -3 \end{bmatrix}$$

PRACTICE PROBLEMS

- 1. Compute A^8 , where $A = \begin{bmatrix} 4 & -3 \\ 2 & -1 \end{bmatrix}$.
- 2. Let $A = \begin{bmatrix} -3 & 12 \\ -2 & 7 \end{bmatrix}$, $\mathbf{v}_1 = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$, and $\mathbf{v}_2 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$. Suppose you are told that \mathbf{v}_1 and \mathbf{v}_2 are eigenvectors of A. Use this information to diagonalize A.
- 3. Let A be a 4×4 matrix with eigenvalues 5, 3, and -2, and suppose you know that the eigenspace for $\lambda = 3$ is two-dimensional. Do you have enough information to determine if A is diagonalizable?

$$\mathbf{u} = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix} \quad \text{and} \quad \mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$$

then the inner product of \mathbf{u} and \mathbf{v} is

$$\begin{bmatrix} u_1 & u_2 & \cdots & u_n \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} = u_1 v_1 + u_2 v_2 + \cdots + u_n v_n$$

EXAMPLE 1 Compute
$$\mathbf{u} \cdot \mathbf{v}$$
 and $\mathbf{v} \cdot \mathbf{u}$ for $\mathbf{u} = \begin{bmatrix} 2 \\ -5 \\ -1 \end{bmatrix}$ and $\mathbf{v} = \begin{bmatrix} 3 \\ 2 \\ -3 \end{bmatrix}$.

THEOREM 1 Let \mathbf{u}, \mathbf{v} , and \mathbf{w} be vectors in \mathbb{R}^n , and let c be a scalar. Then

a.
$$\mathbf{u} \cdot \mathbf{v} = \mathbf{v} \cdot \mathbf{u}$$

b.
$$(\mathbf{u} + \mathbf{v}) \cdot \mathbf{w} = \mathbf{u} \cdot \mathbf{w} + \mathbf{v} \cdot \mathbf{w}$$

c.
$$(c\mathbf{u}) \cdot \mathbf{v} = c(\mathbf{u} \cdot \mathbf{v}) = \mathbf{u} \cdot (c\mathbf{v})$$

d.
$$\mathbf{u} \cdot \mathbf{u} \ge 0$$
, and $\mathbf{u} \cdot \mathbf{u} = 0$ if and only if $\mathbf{u} = \mathbf{0}$

DEFINITION The length (or norm) of v is the nonnegative scalar $\|\mathbf{v}\|$ defined by $\|\mathbf{v}\| = \sqrt{\mathbf{v} \cdot \mathbf{v}} = \sqrt{v_1^2 + v_2^2 + \dots + v_n^2}, \quad \text{and} \quad \|\mathbf{v}\|^2 = \mathbf{v} \cdot \mathbf{v}$

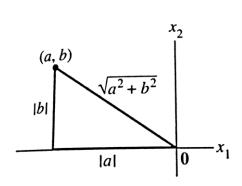
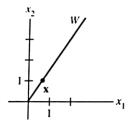


FIGURE 1 Interpretation of ||v|| as length.

$$||c\mathbf{v}|| = |c|||\mathbf{v}||$$

EXAMPLE 2 Let $\mathbf{v} = (1, -2, 2, 0)$. Find a unit vector \mathbf{u} in the same direction as \mathbf{v} .

EXAMPLE 3 Let W be the subspace of \mathbb{R}^2 spanned by $\mathbf{x} = (\frac{2}{3}, 1)$. Find a unit vector \mathbf{z} that is a basis for W.



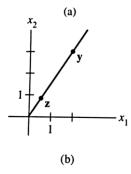


FIGURE 2

Normalizing a vector to produce a unit vector.

Distance in \mathbb{R}^n

We are ready now to describe how close one vector is to another. Recall that if a and b are real numbers, the distance on the number line between a and b is the number |a-b|. Two examples are shown in Figure 3. This definition of distance in \mathbb{R} has a direct analogue in \mathbb{R}^n .

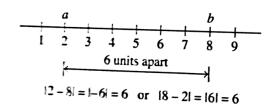
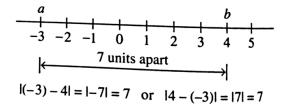


FIGURE 3 Distances in R.



EXAMPLE 4 Compute the distance between the vectors $\mathbf{u}=(7,1)$ and $\mathbf{v}=(3,2)$ SOLUTION Calculate

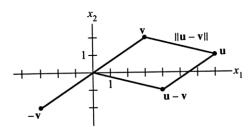


FIGURE 4 The distance between \mathbf{u} and \mathbf{v} is the length of $\mathbf{u} - \mathbf{v}$.

EXAMPLE 5 If $\mathbf{u} = (u_1, u_2, u_3)$ and $\mathbf{v} = (v_1, v_2, v_3)$, then

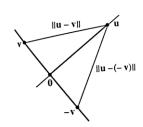


FIGURE 5

DEFINITION Two vectors \mathbf{u} and \mathbf{v} in \mathbb{R}^n are **orthogonal** (to each other) if $\mathbf{u} \cdot \mathbf{v} = 0$.

THEOREM 2 The Pythagorean Theorem Two vectors \mathbf{u} and \mathbf{v} are orthogonal if and only if $\|\mathbf{u} + \mathbf{v}\|^2 = \|\mathbf{u}\|^2 + \|\mathbf{v}\|^2$.

THEOREM 2

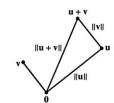


FIGURE 6



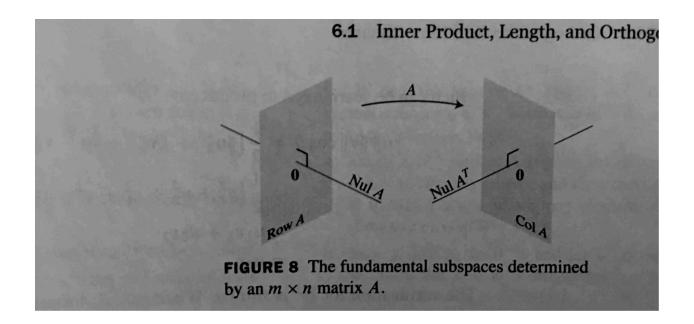
FIGURE 7
A plane and line through 0 as orthogonal complements.

EXAMPLE 6 Let W be a plane through the origin in \mathbb{R}^3 , and let L be the line hrough the origin and perpendicular to W. If \mathbf{z} and \mathbf{w} are nonzero, \mathbf{z} is on L, and \mathbf{w} s in W, then the line segment from $\mathbf{0}$ to \mathbf{z} is perpendicular to the line segment from $\mathbf{0}$ to \mathbf{w} ; that is, $\mathbf{z} \cdot \mathbf{w} = 0$. See Figure 7. So each vector on L is orthogonal to every \mathbf{w} in W. In fact, L consists of all vectors that are orthogonal to the \mathbf{w} 's in W, and W consists of all vectors orthogonal to the \mathbf{z} 's in L. That is,

$$L = W^{\perp}$$
 and $W = L^{\perp}$

The following two facts about W^{\perp} , with W a subspace of \mathbb{R}^n , are needed later n the chapter. Proofs are suggested in Exercises 29 and 30. Exercises 27–31 provide excellent practice using properties of the inner product.

- 1. A vector \mathbf{x} is in W^{\perp} if and only if \mathbf{x} is orthogonal to every vector in a set that spans W.
- 2. W^{\perp} is a subspace of \mathbb{R}^n .



THEOREM 3 Let A be an $m \times n$ matrix. The orthogonal complement of the row space of A is the null space of A, and the orthogonal complement of the column space of A is the null space of A^T :

$$(\operatorname{Row} A)^{\perp} = \operatorname{Nul} A$$
 and $(\operatorname{Col} A)^{\perp} = \operatorname{Nul} A^{T}$

$$\mathbf{u} \cdot \mathbf{v} = \|\mathbf{u}\| \|\mathbf{v}\| \cos \vartheta \tag{2}$$

To verify this formula for vectors in \mathbb{R}^2 , consider the triangle shown in Figure 9, with sides of lengths $\|\mathbf{u}\|$, $\|\mathbf{v}\|$, and $\|\mathbf{u} - \mathbf{v}\|$. By the law of cosines,

$$\|\mathbf{u} - \mathbf{v}\|^2 = \|\mathbf{u}\|^2 + \|\mathbf{v}\|^2 - 2\|\mathbf{u}\| \|\mathbf{v}\| \cos \vartheta$$

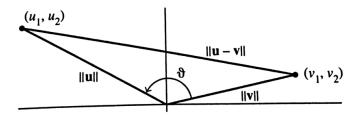


FIGURE 9 The angle between two vectors.

PRACTICE PROBLEMS

1. Let
$$\mathbf{a} = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$$
 and $\mathbf{b} = \begin{bmatrix} -3 \\ 1 \end{bmatrix}$. Compute $\frac{\mathbf{a} \cdot \mathbf{b}}{\mathbf{a} \cdot \mathbf{a}}$ and $\left(\frac{\mathbf{a} \cdot \mathbf{b}}{\mathbf{a} \cdot \mathbf{a}}\right) \mathbf{a}$.
2. Let $\mathbf{c} = \begin{bmatrix} 4/3 \\ -1 \\ 2/3 \end{bmatrix}$ and $\mathbf{d} = \begin{bmatrix} 5 \\ 6 \\ -1 \end{bmatrix}$.

- a. Find a unit vector u in the direction of c.
- b. Show that **d** is orthogonal to **c**.
- c. Use the results of (a) and (b) to explain why **d** must be orthogonal to the unit vector **u**.
- 3. Let W be a subspace of \mathbb{R}^n . Exercise 30 establishes that W^{\perp} is also a subspace of \mathbb{R}^n . Prove that dim $W+\dim W^{\perp}=n$.